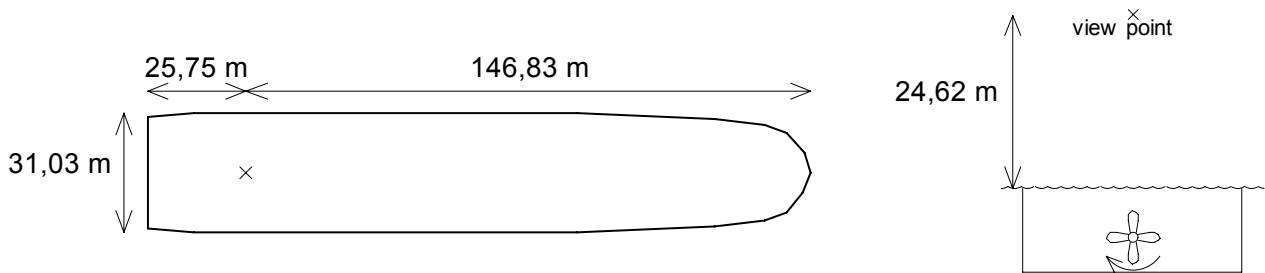


PILOT CARD TANK06L

Ship's name	<u>M/S Stolt Confidence</u>	Date	
Call Sign	Deadweight	tonnes	Year built
Draught aft	<u>11,9</u> m	Forward	<u>11,9</u> m
	<u>39</u> ft <u>0</u> in		<u>39</u> ft <u>0</u> in
		Displacement	<u>37 000,</u> tonnes

SHIP'S PARTICULARS

Length overall	<u>176,8</u> m	Anchor chain: Port	<u>22,1</u> shackles	Starboard	<u>22,1</u> shackles
Breadth	<u>31,03</u> m	Stern	<u>N/A</u> shackles		
Bulbous bow	<u> </u> (yes/no)	(1 shackle = <u>27.4</u> m = <u>15</u> fathoms)			



Type of engine	Maximum power		10 000 kW	13 597 hp
Manoeuvring engine order	RPM	Pitch	Speed (knots)	
			Loaded	Ballast
Full sea speed	85,0	0,831	17,5	
Full ahead	79,0	0,831	16,6	
Half ahead	70,5	0,831	15,0	
Slow ahead	54,0	0,831	10,2	
Dead slow ahead	25,5	0,831	2,6	
Dead slow astern	-25,5	0,831	Time limit astern _____ min:sec	
Slow astern	-54,0	0,831	Full ahead to full astern <u>02:01</u> min:sec	
Half astern	-70,5	0,831	Max. No. of consecutive starts <u>∞</u>	
Full astern	-85,0	0,831	Minimum RPM _____ knots	
			Astern power _____ % ahead	

STEERING PARTICULARS

Type of rudder becker

Maximum angle 60, deg

Hard-over to hard-over 12, s

Rudder angle for neutral effect 0 deg

Thruster:	Bow	<u>1 100</u> kW	<u>1,006</u> hp
		<u>N/A</u> kW	<u>N/A</u> hp
		<u>N/A</u> kW	<u>N/A</u> hp

Stern	<u>N/A</u> kW	<u>N/A</u> hp
	<u>N/A</u> kW	<u>N/A</u> hp
	<u>N/A</u> kW	<u>N/A</u> hp

CHECKED IF ABOARD AND READY

Anchors		<input type="checkbox"/>	
Whistle		<input type="checkbox"/>	
Radar	<input type="checkbox"/> 3 cm	<input type="checkbox"/>	10 cm
ARPA		<input type="checkbox"/>	
Speed log	<input type="checkbox"/> Doppler:	<input type="checkbox"/>	Yes/No
Water speed		<input type="checkbox"/>	
Ground speed		<input type="checkbox"/>	
Dual-axis		<input type="checkbox"/>	
Engine telegraphs		<input type="checkbox"/>	
Steering gear		<input type="checkbox"/>	
Number of power units operations		<input type="checkbox"/>	

Indicators:		<input type="checkbox"/>
Rudder		<input type="checkbox"/>
Rpm/pitch		<input type="checkbox"/>
Rate of turn		<input type="checkbox"/>
Compass system		<input type="checkbox"/>
Constant gyro error ±	<input type="checkbox"/>	deg
VHF		<input type="checkbox"/>
Elec. pos. fix. system		<input type="checkbox"/>
Type	<input type="checkbox"/>	

OTHER INFORMATION: